

Dítec
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## Ditec CS12E

Control panel installation manual for Ditec NEOS automations (Translation of the original instructions)


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## Key

This symbol indicates instructions or notes regarding safety, to which special attention must be paid.

This symbol indicates useful information for the correct functioning of the product.

## Factory settings

## 1. General safety precautions



Failure to observe the information given in this manual may lead to personal injury or damage to the equipment. Keep these instructions for future reference

This installation manual is intended for qualified personnel only. Installation, electrical connections and adjustments must be performed in accordance with Good Working Methods and in compliance with the present standards.
This product must only be used for the specific purpose for which it was designed. Any other use is to be considered improper and therefore dangerous. The manufacturer cannot be held responsible for any damage caused by improper, incorrect or unreasonable use.
Read the instructions carefully before installing the product. Incorrect installation could be dangerous.

The packaging materials (plastic, polystyrene, etc.) should not be discarded in
the environment or left within reach of children, as they are a potential source of danger.
Before installing the product, make sure it is in perfect condition.
Do not install the product in explosive areas and atmospheres: the presence of inflammable gas or fumes represents a serious safety hazard.
The safety devices (photocells, safety edges, emergency stops, etc.) must be installed taking into account the applicable laws and directives, Good Working Methods, installation premises, system operating logic and the forces developed by the automation. Before connecting the power supply, make sure the plate data correspond to those of the mains power supply. An omnipolar disconnection switch with a contact opening distance of at least 3 mm must be fitted on the mains supply.
Check that there is an adequate residual current circuit breaker and a suitable overcurrent cut-out upstream of the electrical installation in accordance with Good Working Methods and with the laws in force.
When requested, connect the automation to an effective earthing system that complies with current safety standards.


During installation, maintenance and repair operations, cut off the power supply before opening the cover to access the electrical parts.
The electronic parts must be handled using earthed antistatic conductive arms. The manufacturer of the motorisation device declines all responsibility if component parts not compatible with safe and correct operation are fitted.
Only use original spare parts when repairing or replacing products.

### 1.1 Safety functions

The CS12E control panel has the following safety functions:

- obstacle recognition with force limiting;

The maximum response time of the safety functions is 0.5 s . The reaction time to a faulty safety function is 0.5 s .
The safety functions comply with the standards and performance level indicated below:
EN ISO 13849-1:2008 Category 2 PL=c
EN ISO 13849-2:2012
The safety function cannot be bypassed either temporarily or automatically. Fault exclusion has not been applied.

## 2. EC Declaration of Conformity

The manufacturer Entrematic Group AB, with headquarters in Lodjursgatan 10, SE-261 44 Landskrona, Sweden, declares that the Ditec CS12E type control panel complies with the conditions of the following EC directives:

2014/30/EU (EMCD)
2014/35/EU (LVD)
2014/53/EU (RED)

Landskrona, 2020-11-26

Matteo Fino


## 3. Technical specifications

| Description | NES400EH | NES600EH | NES600EHSF |
| :---: | :---: | :---: | :---: |
| Power supply | 230V $\sim 50 / 60 \mathrm{~Hz}$ | 230V $50 / 60 \mathrm{~Hz}$ | $230 \mathrm{~V} \sim 50 / 60 \mathrm{~Hz}$ |
| Motor output | $24 \mathrm{~V}=14 \mathrm{~A}$ max | 24V $=16 \mathrm{~A}$ max | 24V =-16A max |
| Accessories power supply | $24 \mathrm{~V}=0.3 \mathrm{~A}$ max | 24V $=0,3 \mathrm{~A}$ max | 24V -.. 0,3A max |
| Operating temperature | - | $\int_{-20^{\circ} \mathrm{C}}^{+55^{\circ} \mathrm{C}}$ | $\underbrace{+55^{\circ} \mathrm{C}}_{-20^{\circ} \mathrm{C}}$ |
| Storable radio codes | $\begin{aligned} & 100 \\ & 200 \text { [BIXMR2] } \end{aligned}$ | $\begin{aligned} & 100 \\ & 200 \text { [BIXMR2] } \end{aligned}$ | $\begin{aligned} & 100 \\ & 200 \text { [BIXMR2] } \end{aligned}$ |
| Radio frequency | $433,92 \mathrm{MHz}$ | $433,92 \mathrm{MHz}$ | $433,92 \mathrm{MHz}$ |

## 4. Commands

| Command |  | Function | Description |
| :---: | :---: | :---: | :---: |
| 1 - - 5 | NO | STEP-BY-STEP WITH AUTOMATIC CLOSING | When selecting $B[\rightarrow[5 \rightarrow 1-5$. closing the contact starts a sequential opening or closing operation: opening-stop-closing-opening. <br> WARNING: if automatic closing is enabled, the duration of the stop can be selected by selecting $B[\rightarrow$ 55. |
|  |  | STEP-BY-STEP WITHOUT AUTOMATIC CLOSING | When selecting $B[\rightarrow[5 \rightarrow \mid-5$, closing the contact starts a sequential opening or closing operation: opening-stop-closing-opening. |
|  |  | OPENING WITH AUTOMATIC CLOSING | When selecting $B[\rightarrow[5 \rightarrow \mid-]$. closing the contact activates an opening operation. |
|  |  | OPENING WITHOUT AUTOMATIC CLOSING | When selecting $B[\rightarrow[5 \rightarrow \mid-3$. closing the contact activates an opening operation. <br> NOTE: Once the automation stops, command 1-5 performs the opposite operation to the one performed before the stop. |
| $1 \longrightarrow 6$ | NC | $\begin{aligned} & \text { CLOSING } \\ & \text { SAFETY DEVICE } \end{aligned}$ | When selecting $B[\rightarrow 54 \rightarrow 1-E$. opening of the safety contact stops and prevents any movement. <br> NOTE: to set different safety contact functions, see the RP $\rightarrow \bar{\Sigma} M$ parameter settings. |
| 1 -- 6 | NO | CLOSING | When selecting $B[\rightarrow 54 \rightarrow 1-4$. closing the contact activates a closing operation. |
| $1 \longrightarrow 8$ | NC | CLOSING SAFETY DEVICE | Opening the safety contact triggers a reversal of the movement (reopening) during the closing operation. When selecting $B[\rightarrow \bar{\zeta} \square \rightarrow \square \mathrm{~N}$, with the automation idle, opening of the contact prevents any operation. <br> When selecting $B[\rightarrow \bar{\beth} \square \rightarrow \square F$, with the automation idle, opening of the contact only prevents closing. |

WARNING: make a jumper for all NC contacts if not in use. The terminals with the same number are equal.

### 4.1 Inserting plug-in card (AUX)

To access the plug-in card (AUX), cut the control panel cover as shown in the figure.


### 4.2 SOFA1-SOFA2 or GOPAVRS self-controlled safety edge

| Command |  | Function | Description |
| :---: | :---: | :---: | :---: |
| $\begin{aligned} & \text { SOFA1-SOFA2 } \\ & \text { GOPAV } \\ & \hline \end{aligned}$ |  | SAFETY TEST | Place the SOFA1-SOFA2 or GOPAVRS device into the special housing for AUX plug-in cards. If the test fails, an alarm message appears on the display. |
| $\circ \circ 0$ |  |  |  |
| $1 \longrightarrow 6$ | NC | SAFETY STOP | When selecting RP $\rightarrow$ \#G $\rightarrow 541$, connect the output contact of the safety device to terminals 1-6 on the control panel (in series with the photocell output contact, if installed). |
| $1 \longrightarrow 8$ | NC | CLOSING SAFETY DEVICE | When selecting RP $\rightarrow 7 B \rightarrow 541$, connect the output contact of the safety device to terminals 1-8 on the control panel lin series with the photocell output contact, if installed). |

Examples of installation of self-controlled safety edge


## 5．Outputs and accessories

| Output | Value <br> Accessories | Description |
| :---: | :---: | :---: |
|  | $24 \mathrm{~V}=0.3 \mathrm{~A}$ | Accessories power supply． <br> External accessories power supply output． <br> NOTE：the maximum absorption of 0.3 A corresponds to the sum of all terminals 1. |
|  | $\begin{aligned} & \text { GOL148REA } \\ & (433,92 \mathrm{MHz}) \end{aligned}$ | Antenna connection（433， 92 MHz ）． <br> If the inside radio receiver is used，connect the supplied antenna wire（ 173 mm ），or alternatively the GOL148REA antenna，using a coaxial cable，type RG58． |
|  | $\begin{gathered} \text { FL24 } \\ \text { FLM } \\ 24 \mathrm{~V}=25 \mathrm{~W} \end{gathered}$ | Flashing light． <br> The pre－flashing settings can be selected from the third level menuRP $\rightarrow W$ and／or RP $\rightarrow W[$. |
| AUX |  | The control panel has a housing for plug－in cards． <br> The action of the card can be selected by selecting B［ $\rightarrow$ RM． WARNING：the plug－in cards must be inserted and removed with the power supply disconnected． |
| COM | BIXMR2 | This allows the functioning configurations to be saved using the function $\bar{\jmath} F \rightarrow \zeta \mathrm{~b}$＇． <br> The saved configurations can be recalled using the function 5F $\rightarrow$ R［． |
|  |  | The storage module allows the remote controls to be stored． If the control panel is replaced，the storage module being used can be inserted in the new control panel． <br> WARNING：the storage module must be inserted and re－ moved with the power supply disconnected． |
| $\frac{\mid \text { 凅國 }}{\text { LSW }}$ | NES100FCM | Magnetic limit switch kit（optional only for Ditec NES400）． |
| $\frac{\text { 回回 }}{\text { BAT }}$ | $\begin{gathered} \text { SBU } \\ 2 \times 12 \mathrm{~V} 2 \mathrm{Ah} \end{gathered}$ | BAT－Batteries functioning． <br> The batteries are kept charged when the power supply is on．If the power supply is off，the panel is powered by the batteries until the power is re－establish or until the battery voltage drops below the safety threshold．The panel turns off in the last case． WARNING：the batteries must always be connected to the con－ trol panel for charging．Periodically check the efficiency of the batteries． <br> NOTE：the operating temperature of the rechargeable batteries is approximately $+5^{\circ} \mathrm{C} /+40^{\circ} \mathrm{C}$ ． |
|  |  | Mains power supply，motor，release microswitch and automa－ tion wiring connection． |

## 6. Selections

| Jumper | Description | OFF | ON |
| :---: | :--- | :--- | :--- |
| JR1 | Display mode selection. | Display mode. <br> Only the values and pa- <br> rameters present can be <br> displayed. | Maintenance mode. <br> Only the values and parameters pre- <br> sent can be displayed and modified. <br> Going into maintenance mode is indi- <br> cated by the permanent switching on <br> of the right-hand point on the display. |
| JR3 | Built-in radio receiver. | Disabled. | Enabled. |

## 7. Settings



Some parameters of the NeoS SUPERFAST have been limited for functional safety reasons (given the maximum reachable speed). For special needs, contact technical assistance.


NOTE: pressure on the keys can be quick (less than 2 s) or prolonged (longer than 2 s). Unless specified otherwise, quick pressure is intended.
i
NOTE: depending on the type of automation and control panel, some menus may not be available.

### 7.1 Switching the display on and off

The procedure to switch on the display is as follows:


- press the ENTER key

- the display functioning check starts

- the first level menu is displayed


The procedure to switch off the display is as follows:

- press the ESC key


NOTE: the display switches off automatically after 60 s of inactivity.

### 7.2 Key combinations

- Simultaneous pressing of the keys $\uparrow$ and ENTER performs an opening command.

- $\quad$ Simultaneous pressing of the keys $\downarrow$ and ENTER performs a closing command.

- Simultaneous pressing of the keys $\uparrow$ and $\downarrow$ performs a POWER RESET command. (interruption of the power supply and restart of the automation).

- Keeping press the UP $\uparrow$ or DOWN $\downarrow$ key, fast menu scrolling begin. To stop menu scrolling.
- In some menus, the parameter unit of measurement can be displayed by pressing the ENTER key once the value has been displayed (in the example, 50 cm ).



### 7.3 Main menu

- using keys $\uparrow$ and $\downarrow$ select the desired function

- press the ENTER key to confirm


## ENTER

After confirming the selection, you access the second level menu.

| Description |
| :--- | | BT - Automatic Configurations. |
| :--- |
| The menu allows you to manage the automatic configurations of the control |
| Panel. |

### 7.4 Second level menu AT (Automatic Configurations)

- using keys $\uparrow$ and $\downarrow$ select the desired function

- press the ENTER key to confirm


## ENTER




### 7.5 Second level menu - BC (Basic Configurations)

- using keys $\uparrow$ and $\downarrow$ select the desired function

- press the ENTER key to confirm


## ENTER



7．5．1 Additional BC level parameters that can be configured （available with 日T $\rightarrow$ 月月 enabled）

|  | Display | Description |  |  |
| :---: | :---: | :---: | :---: | :---: |
|  | － | HR－Enabling of operator present function <br> ON－Enabled <br> OF－Disabled <br> NOTE：Set HR $\rightarrow$ O Nonly if $54 \rightarrow 1$－ and［ $[5 \rightarrow$ | EMv | EF |
|  | ［］$\square_{1}$ | 64 －Functioning of safety stop／closing command． <br> 1－4－Closing <br> 1－6－Safety stop | 1－L－1 | 1－ |
| M | $[\square$ | C5－Step－by－step／opening command operation． <br> 1－5－Step－by－step <br> 1－3－Opening | 1－5 | $1-3$ |
|  | 回少 | RM－Radio receiver operation． <br> 1－5－Step－by－step <br> 1－3－Opening | $1-5$ | $1-\beth$ |
|  | FN1 | AM－AUX plug－in card operation． <br> 1－5－Step－by－step <br> 1－3－Opening | 1－5 | $1-3$ |
|  | $\square$ | PP－Setting step－by－step sequence from command 1－5． ON－Opening－Stop－Closing－Stop－Opening OF－Opening－Stop－Closing－Opening | ■心思 | FF |
|  | ${ }_{\square}^{1}$ | S5－Duration of STOP in step－by－step sequence from command 1－5． <br> ON－Permanent <br> OF－Temporary | Hiv | TF |
|  | $\square 1$ | OD－Selecting opening direction． <br> LF－Opening to left． <br> RT－Opening to right． <br> The opening direction is intended by viewing the auto－ mation from the side being examined． <br> NOTE：Modification of status from RT to LF and vice ver－ sa performs an automatic RESET of the card． | 15 | $\square 1$ |

### 7.6 Second level menu - BA (Basic Adjustment)

- using keys $\uparrow$ and $\downarrow$ select the desired function

- press the ENTER key to confirm


## ENTER

|  | Display | Description |  |
| :---: | :---: | :---: | :---: |
|  | M1 T | MT - Display of type of automation. <br> N3 - Motor with 300 kg capacity <br> N4 - Motor with 400 kg capacity <br> N6 - Motor with 600 kg capacity <br> SF - Motor SUPERFAST with 600 kg capacity <br> NOTE: this parameter is DISPLAY only. |  |
| $\stackrel{1}{6}$ | $11$ | TC - Setting of automatic closing time. [s] It is set with different intervals of sensitivity. <br> - from 0" to 59 " with intervals of 1 second; <br> - from 1' to $2^{\prime}$ with intervals of 10 seconds. |  |
| \% | $\square \square$ | RP - Adjustment of partial opening measurement. [\%] Adjusts the percentage of operation in relation to the total opening of the automation. <br> 10 - Minimum <br> 99 - Maximum | $\frac{1 \sqrt{1}+\square}{30}$ |
| $\begin{gathered} \mathrm{m} \\ \frac{1}{\mathrm{~L}} \end{gathered}$ | $15$ | TP - Setting of automatic closing time after partial opening. [s] <br> It is set with different intervals of sensitivity. <br> - from 0 " to 59 " with intervals of 1 second; <br> - from $1^{\prime}$ to $2^{\prime}$ with intervals of 10 seconds. | $\left.\begin{array}{ccc} \sqrt{1} & \square & \square \\ 1 \mid & -1 & -1 \end{array}\right)$ |
|  | $1^{\prime} F$ | VA - Setting of opening speed. [cm/s] NOTE: <br> 24 - Maximum with MT $\rightarrow$ NG <br> 25 - Maximum with MT $\rightarrow$ N 3 or NH <br> 40 - Maximum with MT $\rightarrow \overline{5} F$ |  |


|  | Display | Description |  |
| :---: | :---: | :---: | :---: |
|  |  | VC - Setting of closing speed. [cm/s] NOTE: <br> 24 - Maximum with MT $\rightarrow$ NE <br> 25 - Maximum with MT $\rightarrow$ N 3 or NV 4 | $\begin{array}{ccc} 15 \\ 15 \end{array}$ |
| ) |  | 40 - Maximum with MT $\rightarrow$ JF | NeoS SUPERFAST |
| $\bigcirc$ |  | R2 - Adjustment of thrust on obstacles and current during opening [\%] <br> The control panel is equipped with a safety device that stops movement if an obstacle is detected during an opening operation with disengagement of 10 cm . <br> 00 - Minimum thrust <br> 99 - Maximum thrust | $\frac{\sqrt{1} \sqrt{1}}{50}$ |
| $\frac{1}{\mathrm{~m}}$ | $\left[\begin{array}{ll} -1 & 1 \end{array}\right.$ | R1 - Adjustment of thrust on obstacles and current during closing [\%] <br> The control panel is fitted with a safety device which stops or reverses movement when an obstacle is detected during a closing operation. <br> 00 - Minimum thrust <br> 99 - Maximum thrust | $\frac{\sqrt{1} \sqrt{1},}{1}$ |

WARNING: make adjustments gradually and only after performing at least three complete operations to allow the control panel to be set correctly and detect any friction during operations.

7．6．1 Additional BA level parameters that can be configured （available with $\boldsymbol{\text { R }} \boldsymbol{T} \rightarrow$ 月月 enabled）

|  | Display | Description |  |
| :---: | :---: | :---: | :---: |
|  | II 1 | DT－Adjustment of obstacle recognition time．［s／100］ <br> 10 －Minimum <br> 60 －Maximum <br> NOTE：the parameter is adjusted in hundredths of a second | $\begin{gathered} 15 \overline{1}+\overline{1} \\ 40 \end{gathered}$ |
|  | 91F | MP－Start at maximum power <br> ON－During start－up it increases the thrust on obstacles to maximum． <br> OFF－During start－up the thrust on obstacles is that ad－ justed by P 1－R ？ | GivFF |
|  | ［ 1 | ST－Adjustment of start time．［s］ <br> 0.5 －Minimum <br> 3.0 －Maximum <br> Neos SUPERFAST <br> 1.0 －Minimum <br> 4.0 －Maximum |  |
| ๓ |  | TA－Adjustment of acceleration time．［s］ （start speed is $75 \%$ of $b^{\prime}$ 月－$b^{\prime}$［） <br> 0.5 －Minimum <br> 2.0 －Maximum <br> NeoS SUPERFAST <br> 1.0 －Minimum <br> 4.0 －Maximum |  |
|  | T II | TD－Adjustment of deceleration time．［\％］ <br> 10 －Minimum <br> 99 －Maximum <br> NeoS SUPERFAST <br> 10 －Minimum <br> 75 －Maximum <br> NOTE NeoS SUPERFAST：In some cases，on light gates，it is possible to set this value above the indicated maxi－ mum value．If necessary，contact technical assistance． |  |
|  | $\square$ | OB－Adjustment of deceleration distance during opening．［cm］ Indicates the distance from the end of the opening stroke where the deceleration ramp begins． <br> 05 －Minimum <br> 99 －Maximum <br> NOTE：reduce the deceleration space if there is a series of quick vibrations（chattering）in heavy gates installed with a slight incline． <br> NeoS SUPERFAST： <br> 75 －Minimum <br> 99 －Maximum <br> NOTE NeoS SUPERFAST：In some cases，on light gates，it is possible to set this value above the indicated minimum value．If necessary，contact technical assistance． | NeoS SUPERFAST |



WARNING: make adjustments gradually and only after performing at least three complete operations to allow the control panel to be set correctly and detect any friction during operations.

### 7.7 Second level menu - RO (Radio Operations)

- using keys $\uparrow$ and $\downarrow$ select the desired function

- press the ENTER key to confirm


## ENTER




7．7．1 Additional RO level parameters that can be configured （available with $口 T \rightarrow$ 月月 enabled）


### 7.8 Second level menu - SF (Special Functions)

- using keys $\uparrow$ and $\downarrow$ select the desired function

- press the ENTER key to confirm


## ENTER



### 7.8.1 Additional SF level parameters that can be configured lavailable with RT $\rightarrow$ 月月 enabled)

Display
SP - Setting the password.

### 7.9 Second level menu - CC (Cycles Counter)

- using keys $\uparrow$ and $\downarrow$ select the desired function

- press the ENTER key to confirm



7．9．1 Additional CC level parameters that can be configured lavailable with $口 T \rightarrow$ 月月 enabled）


### 7.10 Second level menu - AP (Advanced Parameters)

- using keys $\uparrow$ and $\downarrow$ select the desired function

- press the ENTER key to confirm


## ENTER

| $\begin{gathered} 0 \\ \frac{0}{0} \\ \frac{1}{0} \\ \frac{8}{0} \\ 0 \\ 0 \end{gathered}$ | Display |  |  |  |
| :---: | :---: | :---: | :---: | :---: |
|  | $E 1$ | Description <br> FA - Selection of opening limit switch mode. <br> NO - None <br> SX - Stop limit switch lafter activation the door wing stops its movement) <br> PX - Proximity limit switch lafter activation the door wing continues as far as the end stop and any obstacle is considered a stop) (with standard limit switches) | NES400EH $\begin{array}{ll} \text { it } \\ \text { iv } \end{array}$ | NES600EH/SF <br> N |
|  | FI | FC - Selection of closing limit switch mode. <br> NO - None <br> SX - Stop limit switch lafter activation the door wing stops its movement) <br> PX - Proximity limit switch lafter activation the door wing continues as far as the end stop and any obstacle is considered a stop) <br> awno (with standard limit switches) | $\begin{aligned} & \text { NES4OOEH } \\ & \text { M I } \\ & \text { IV } \end{aligned}$ | NES600EH/SF $\square$ <br> N |
|  |  | D6 - Selection of device connected to terminals 1-6. <br> NO - None <br> SE - Safety edge lif contact 1-6 opens, after stopping, there is a disengagement of 10 cm ) <br> S41 - Safety edge with safety test lif contact 1-6 opens, after stopping, there is a disengagement of 10 cm ) <br> PH - Photocells <br> P41 - Photocells with safety test | $\begin{aligned} & A 15 \\ & \text { iv } \\ & \text { F } 41 \\ & -141 \\ & 141 \end{aligned}$ | $\begin{aligned} & E E \\ & \square E 1 \end{aligned}$ |
|  | I1 | D8-Selection of device connected to terminals 1-8. <br> NO - None <br> SE - Safety edge <br> S41 - Safety edge with safety test <br> PH - Photocells <br> P41 - Photocells with safety test |  | $\begin{aligned} & 5 E \\ & \square E 1 \end{aligned}$ |


| $\cdots$ | Display | Description |  |  |
| :---: | :---: | :---: | :---: | :---: |
|  |  | DS - Setting of display visualisation mode. <br> 00 - No display <br> 01 - Commands and safety devices with radio test (see paragraph 8.2). <br> Display of count down to automatic closing. <br> 02 - Automation status (see paragraph 8.1) <br> 03 - Commands and safety devices (see paragraph 8.2) |  | $\begin{array}{ll} \Gamma 1 & 1 \\ V 1 & 1 \\ V & 1 \\ 1 & 1 \end{array}$ |

WARNING: make adjustments gradually and only after performing at least three complete operations to allow the control panel to be set correctly and detect any friction during operations.
7.10.1 Additional AP level parameters that can be configured lavailable with $\cap T \rightarrow$ 月月 enabled)


Display | Description |
| :--- |
| TN - Setting of intervention temperature for NIO anti- |
| freeze system. [${ }^{\circ} \mathrm{C}$ ] |
| Adjustment of the working temperature of the control pan- |
| el. The value does not refer to ambient temperature. |

WARNING: make adjustments gradually and only after performing at least three complete operations to allow the control panel to be set correctly and detect any friction during operations.

## 8．Display visualisation mode



NOTE：depending on the type of automation and control panel，some menus may not be available．

## 8．1 Display of automation status

1 The automation status display mode is only visible with Display visualisation mode set to 02 ．
月ア $\rightarrow$ 卫ら $\rightarrow$ ロ

| Display | Description |
| :---: | :---: |
|  | $\left[\begin{array}{ll} \pi & \square \\ 1 & 1 \end{array}\right.$ |
| $\underline{1}-1$ | Automation closed． |
| I － | Automation closed．Release door open． |
| 1 | Automation open． |
| ． 1 | Automation open．Release door open． |
| 1 | Automation stopped in intermediate position． |
| ＋ | Automation stopped in intermediate position．Release door open． |
| $\begin{array}{ll}1 \\ \text { v } & 1 \\ \end{array}$ | Automation closing． |
| V | Automation that slows down during closing． |
| $\begin{array}{ll}1 \\ 1 & N \\ V & V\end{array}$ | Automation opening． |
| N | Automation that slows down during opening． |


| Display | Description |
| :---: | :---: |
|  | $\square 1+1$ |
| -1 7 <br> - -1 | Automation closed. |
| -1  <br> .- -1 | Automation closed. Release door open. |
| I | Automation open. |
| 1. | Automation open. Release door open. |
| $\square$ | Automation stopped in intermediate position. |
| -1 | Automation stopped in intermediate position. Release door open. |
| 1 1 <br> $V$ $N$ | Automation closing. |
| N | Automation that slows down during closing. |
| (1) $\begin{array}{ll}1 & 1 \\ 1 & 1\end{array}$ | Automation opening. |
| V | Automation that slows down during opening. |

## 8．2 Display of safety devices and commands

iThe safety device and command display mode is only visible with Display visualisation mode set to 01 or 03.
AP $\rightarrow$ 卫ら $\rightarrow$ 目 1
AP $\rightarrow$ By $\rightarrow$ Q

## Display Description

I．－1－3－Opening command．

I＿L＿I 1－4－Closing command．
1 I－$\quad$ 1－5－Step－by－step command．

I＿$\quad$ 1－6－Safety device with opening and closing stop．

1．1－8－Safety with closing reversal．
－1 P3－Partial opening command．

3P－Opening command with operator present．

4P－Closing command with operator present．



I
CX－Receipt of command from AUX card．


F1-Closing limit switch

|  | F2-Opening limit switch |
| :---: | :---: |
| $\square 1$ | 01 - Detection of an obstacle during closing |
|  | O2- Detection of an obstacle during opening |
|  | OO-Reaching of obstacle detection limit during opening |
|  | OC - Reaching of obstacle detection limit during closing |
|  | S1 - Detection of stop during closing |

- S2 - Detection of stop during opening

|  | SW - Release door open. |
| :--- | :--- | :--- |
| When the release door is closed, the control panel performs a RESET (alarm |  |
| It is possible to ignore the reset by holding down the ESC \& DOWN keys for 3 sec - |  |
| onds until the SW stops flashing. |  |

### 8.3 Display of alarms and faults

Alarms and faults can be displayed with any display selection. The signalling of alarm messages takes priority over all other displays.

| Type of |
| :--- | :--- | :--- | :--- | :--- |
| alarm |


| Type of alarm | Display | Description | Operation |
| :---: | :---: | :---: | :---: |
|  | $\square$ | R3 - Storage module not detected (with $J R 3=0 N$ ). | Insert a working storage module or set JR3=0FF. |
|  |  | R5 - Storage module not working (regardless of JR3) | Replace the storage module. |
|  |  | AO - Failure of test of safety sensor on contact 6 . | Check that device SOFA1-A2/GOPAV is working correctly. |
|  |  |  | If the supplementary card is not inserted, check that $7 \square$ is not set to $\bar{\square} 41 / P 41$ |
|  |  | A3 - Failure of test of safety sensor on contact 8 . | Check that device SOFA1-A2/GOPAV is working correctly. |
|  |  |  | If the supplementary card is not inserted, check that 78 is not set to $541 / \sim 41$ |
|  | $\square 10$ | A9 - Flashing light output short circuit alarm | Check that the flashing light is working properly. |
|  |  | P1-Microswitch voltage too low | Check the control panel is powered correctly. |
|  | $1 \begin{array}{ll} 1 & 1 \\ 1 & 1 \end{array}$ | 17 - Internal parameter outside limits error | Reset. <br> If the problem persists, contact Technical Support. |
|  |  | 18 - Program sequence error | Reset. <br> If the problem persists, contact Technical Support. |
|  | 1001 | IA - Internal parameter error (EEPROM) | Reset. <br> If the problem persists, contact Technical Support. |
|  | $\begin{array}{ll}1 & 11 \\ 1 & 11\end{array}$ | IB - Internal parameter error (RAM) | Reset. <br> If the problem persists, contact Technical Support. |
|  | $\left[\begin{array}{ll}1 & 1 \\ 1 & 1\end{array}\right.$ | IC - Operation time out error ( $>5 \mathrm{~min}$ or $>7 \mathrm{~min}$ in acquisition mode) | Manually check that the door wing moves freely. <br> If the problem persists, contact Technical Support. |
|  | 11101 | IH - Overcurrent with motor switched off alarm | Reset. <br> If the problem persists, contact Technical Support. |


| Type of alarm | Display | Description | Operation |
| :---: | :---: | :---: | :---: |
|  | 1 $M$ 1 <br> 1 1 1 | IM - Shortcircuited motor MOSFET alarm | Reset. <br> If the problem persists, contact Technical Support. |
|  | $1 \begin{array}{ll}1 & 1 \\ 1 & 1\end{array}$ | 10 - Interrupted power circuit (motor MOSFET open) | Reset. <br> If the problem persists, contact Technical Support. |
|  | 101 | IR- Motor relay malfunctioning | Reset. <br> If the problem persists, contact Technical Support. |
|  | M M | Firmware reset (SIGNAL ONLY) |  |
|  | $1 V^{1 / 1}$ | V0 - Request for maintenance intervention | Proceed with the scheduled maintenance intervention. |

## 9. Start-up



## NeoS SUPERFAST

Pay attention to the adjustment of the slowdown spaces and braking times!
Make adjustments gradually, and only after having completed at least three complete maneuvers, to allow the control panel to calibrate correctly and detect any friction during maneuvers.

1- Make a jumper for NC safety contacts.
2- Adjust the opening and closing stop limit switches, if any.
NOTE: The limit switches must remain pressed until the operation is completed and placed as shown in the Ditec NeoS installation manual.
3- Set the desired opening direction from the $\cap T$ menu.
4- Manually move the sliding gate and make sure the entire stroke slides evenly and without friction.
5- Switch on and check the automation is operating correctly with the subsequent opening and closing commands (see paragraph 7.2).
Check that the limit switches are activated if used.

WARNING
The operations are performed without safety devices.
The display parameters can only be adjusted when the automation is idle.
The automation automatically slows when approaching the end stops or stop limit switches.
At every start-up the control panel receives a RESET and the first operation is performed at reduced speed (automation position acquisition).

6- Connect the safety devices 75 and $70 \rightarrow \overline{3} 41$ (removing the relative jumpers) and check they are working correctly.
7- To modify the operation and deceleration speed settings, automatic closing times and thrust on obstacles, consult the menus.
8- Connect any other accessories and check they are functioning.
WARNING: Ensure that the forces exerted by the door wings are compliant with EN12453EN12445 regulations.
9- If required, store the remote controls using command $尺 \square \rightarrow$ 吅
10- Once the start-up and check procedures are completed, close the container.

NOTE: in the event of servicing or if the control panel is to be replaced, repeat the start-up procedure.

10．Troubleshooting

| Problem | Possible cause | Alarm signalling | Operation |
| :---: | :---: | :---: | :---: |
| The automation does not open or close． | No power． |  | Check power supply cable． |
|  | Short circuited accessories． |  | Disconnect all accessories from terminals 0－1 la voltage of $24 \mathrm{~V}=$ must be present）and reconnect them one at a time． Contact Technical Service |
|  | Blown line fuse． |  | Replace fuse． |
|  | Safety contacts are open． | $1-6$ | Check that the safety contacts are closed correctly（NC）． |
|  | Safety contacts not correctly connected or self－controlled safety edge not functioning correctly． | $\begin{aligned} & 180 \\ & R 3 \\ & 1-6 \\ & 1-8 \end{aligned}$ | Check connections to terminals 6－8 on control panel and con－ nections to the self－controlled safety edge． |
|  | SAFETY SWITCH release mi－ croswitch open． | 亏W | Check that the hatch is closed correctly and the microswitch makes contact． |
|  | Photocells activated． | $\begin{aligned} & 1-6 \\ & 1-9 \end{aligned}$ | Check that the photocells are clean and operating correctly． |
|  | The automatic closing does not work． |  | Issue any command．If the problem persists，contact Technical Service |
|  | Mechanical fault | $\begin{aligned} & M 3 \\ & M B \end{aligned}$ | Check the rack or transmis－ sion chain，and／or the me－ chanical parts． |
|  | Faulty motor | $\begin{aligned} & M 4 \\ & M B \end{aligned}$ | Check motor connection，if the problem persists，contact Technical Service． |
|  | Faulty control panel |  | Contact Technical Service． |
| The external safety devices are not activated． | Incorrect connections be－ tween the photocells and the control panel． |  | Check that $1-5 / 1-日$ is dis－ played <br> Connect NC safety contacts together in series and remove any jumpers on the control panel terminal board． |
|  |  |  | Check the RP $\rightarrow$ DG and RP $\rightarrow$ D日setting |


| The automation opens/closes briefly and then stops. | There is a presence of friction. | $\begin{aligned} & M Q \\ & \frac{M 1}{1}= \\ & \frac{1}{1}= \end{aligned}$ | Manually check that the automation moves freely and check <br>  Contact Technical Service |
| :---: | :---: | :---: | :---: |
| The remote control has limited range and does not work with the automation moving. | The radio transmission is impeded by metal structures and reinforced concrete walls. |  | Install the antenna outside. |
|  |  |  | Replace the transmitter batteries. |
| The remote control does not work | No storage module or incorrect storage module. | $\begin{aligned} & R \square \\ & R \because 3 \\ & R 5 \end{aligned}$ | Switch the automation off and plug in the correct storage module. |
|  |  |  | Check the correct memorisation of the transmitters on the built-in radio. If there is a fault with the radio receiver that is built into the control panel, the remote control codes can be read by removing the storage module. |
| The flashing light is not working | Bulb burnt or flashing light wires detached or short-circuited. | $89$ | Check the bulb and/or wires. Contact Technical Service |

## 11. Examples of sliding gate applications

- set the correct opening direction:



## Example 1 - Door wing stops against mechanical end stops (standard setting)

Set


Example 2 - Door wing stops against limit switches (setting with standard limit switches installed)
Connect the limit switches to the terminal $\begin{aligned} & \text { LSW } \\ & \square \square\end{aligned}$
Set


With these settings, if an obstacle is detected while opening, the door wing stops and performs a disengagement operation whereas during a closing operation, the door wing reopens.

Example 3 - Door wing stops against mechanical end stops and reverses motion if an obstacle is detected
Connect the limit switches to the terminal $\square$
Set


In this configuration, the door wing stops against its respective mechanical closing and opening end stop. In the event of obstacle detection before the activation of the proximity limit switch while opening, the door wing stops, performing a disengagement operation; after the proximity limit switch is activated, the door wing stops against the obstacle.
In the event of obstacle detection during closing and before the activation of the proximity limit switch, the door wing reopens; after the proximity limit switch is activated, the door wing stops against the obstacle.

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